GETTING STARTED WITH THE SENSORS

1. With your team, choose which sensors you want to focus on.
   1. Ultrasonic sensors are more versatile, but a noisier and unreliable if your are trying to sense a corner or at a high angle to your target.
   2. Line following IR sensors require you to follow a line at all times and if you get off the line, then you may not be able to get back.
2. Take a look at the sample code that we have provided you, connect the sensor appropriately and load the code on the Arduino.
3. Look at the outputs the sensors give you and think about what sort of logic you will use to harness that information.
4. If you are not familiar with [if statements](https://www.arduino.cc/en/Reference/If) and [switch-cases](https://www.arduino.cc/en/Reference/SwitchCase) in Arduino click on the links and read the documentation.
5. If you still are not sure what to do, ask and we will help you out.